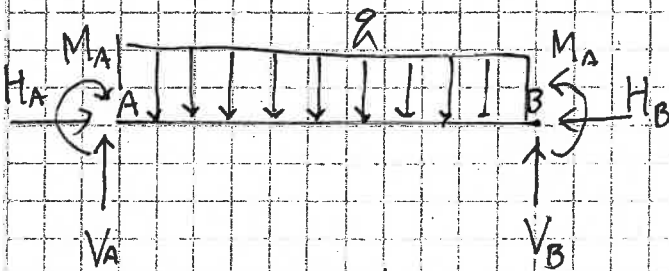
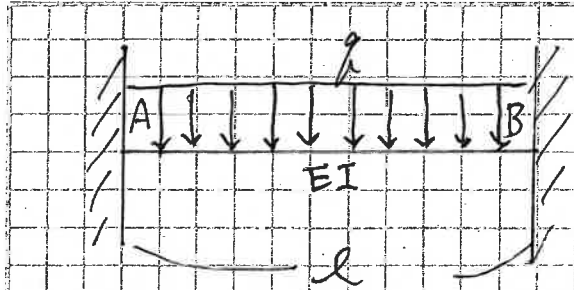


Q) 曲げモーメント図を作成せよ。

1/2



free-body diagram

($\because H_A = H_B = 0$)

③, ④ ← ①, ② へ代入

$$M_{AB} = C_{AB}, \quad M_{BA} = C_{BA}$$

① 中間荷重項 C_{AB}, C_{BA} (表 8.1) 手帳, PK53

$$C_{AB} = -\frac{ql^2}{12}, \quad C_{BA} = \frac{ql^2}{12}$$

$$\therefore M_{AB} = -\frac{ql^2}{12}, \quad M_{BA} = \frac{ql^2}{12}$$

梁理論より M_A と M_B を求めよ

$$M_A = M_{AB} = -\frac{ql^2}{12}, \quad M_B = -M_{BA} = -\frac{ql^2}{12}$$



たわみ角法で解く。

① 材端モーメント

$$M_{AB} = \frac{2EI}{l} (\theta_A + \theta_B - 3R) + C_{AB} \quad \text{--- (1)}$$

$$M_{BA} = \frac{2EI}{l} (\theta_A + 2\theta_B - 3R) + C_{BA} \quad \text{--- (2)}$$

② 境界条件

A点とB点は固定である。

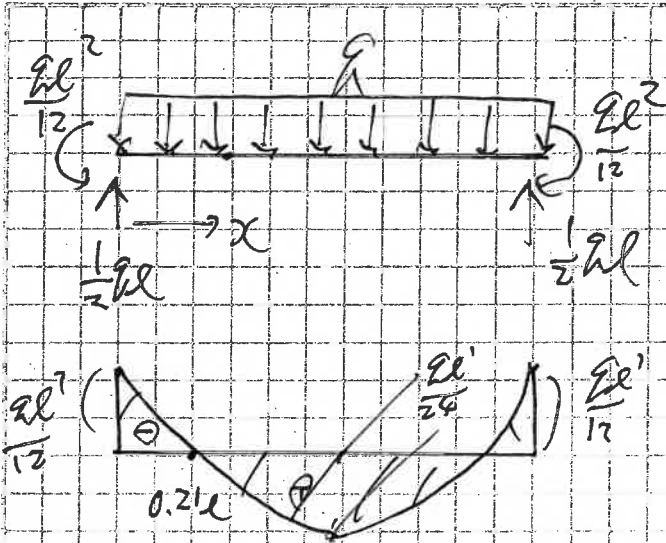
よってたわみ角 $\theta_A = \theta_B = 0$ --- (3)

A点とB点は不動点である

よって $R = 0$ (部材角ゼロ) --- (4)

$$\begin{cases} \sum V = V_A + V_B - ql = 0 \\ \sum M_A = -V_B l - \frac{ql^2}{12} + \frac{ql^2}{12} + \frac{ql^2}{2} = 0 \end{cases}$$

$$V_B = \frac{1}{2} ql = V_A$$



< 曲けり (L/2) >

$$M_x = -\frac{ql^2}{12} + \frac{1}{2}qlx - \frac{1}{2}qx^2 = 0$$

$$-ql^2 + 6qlx - 6qx^2 = 0$$

$$6qx^2 - 6qlx + ql^2 = 0$$

$$\text{解の公式 } x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$a = 6q, b = -6ql, c = ql^2$$

$$x = \frac{6ql \pm \sqrt{36q^2l^2 - 24q^2l^2}}{12q} = \frac{6ql \pm \sqrt{12q^2l^2}}{12q}$$

$$= \frac{6ql \pm 2ql\sqrt{3}}{12q} = \frac{3l \pm \sqrt{3}l}{6}$$

$$x = \frac{3l + \sqrt{3}l}{6} = \frac{3 + \sqrt{3}}{6}l \approx 0.7887l$$

$$= \frac{3l - \sqrt{3}l}{6} = \frac{3 - \sqrt{3}}{6}l \approx 0.2113l$$

$$M_x = -\frac{ql^2}{12} + \frac{1}{2}qlx - \frac{1}{2}qx^2$$

$$x = 0 \text{ or } l$$

$$M_x = -\frac{ql^2}{12}$$

$$x = \frac{l}{2} \text{ or } \frac{3}{4}l$$

$$M_x = -\frac{ql^2}{12} + \frac{ql^2}{4} - \frac{ql^2}{8}$$

$$= \frac{-2 + 6 - 3}{24}ql^2$$

$$= \frac{1}{24}ql^2$$

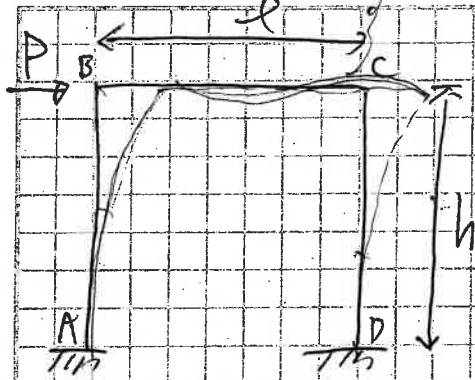
$$x = l \text{ or } 2l$$

$$M_x = -\frac{ql^2}{12}$$

水平移動

問) 曲げモーメントの概略図を求めよ

図の比 $k=1$ とする



① 境界条件

$$\phi_a = \phi_d = 0, \psi_{bc} = \psi_{cb} = 0$$

$C = 0$: 中間荷重なし

$$\psi_{ab} = \psi_{dc} = \psi$$

(=bc) (=cd)

② 材端モーメントの方程式

$$M_{ab} = 2\phi_a + \phi_b + \psi_{ab} + C_{ab}$$

$$= \phi_b + \psi \quad \text{--- (1)}$$

$$M_{ba} = 2\phi_b + \phi_a + \psi_{ba} + C_{ba}$$

$$= 2\phi_b + \psi \quad \text{--- (2)}$$

③ 同様にして

$$M_{bc} = 2\phi_b + \phi_c \quad \text{--- (3)}$$

$$M_{cb} = 2\phi_c + \phi_b \quad \text{--- (4)}$$

$$M_{cd} = 2\phi_c + \psi \quad \text{--- (5)}$$

$$M_{dc} = \phi_c + \psi \quad \text{--- (6)}$$

④ 節点の方程式 (変形適合条件)

$$M_{ba} + M_{bc} = 0, \quad M_{cb} + M_{cd} = 0 \quad \text{--- (7)}$$

⑤ 層の方程式 (力のつりあいの条件)



$$\sum M_b = Q_{ba}h + M_{ba} + M_{ab} = 0$$

$$\therefore Q_{ba} = -\frac{M_{ba} + M_{ab}}{h} \quad \text{--- (10)}$$

$$\sum M_c = Q_{cd}h + M_{cd} + M_{dc} = 0$$

$$\therefore Q_{cd} = -\frac{M_{cd} + M_{dc}}{h} \quad \text{--- (11)}$$

⑨, ⑩, ⑪ を代入して

$$\therefore M_{ba} + M_{ab} + M_{cd} + M_{dc} = -\frac{Ph}{2}$$

~~(1)~~ (7) (8) = ~~(1)~~ (2), (3), (4), (5) ∈ ℝ ∩ ℤ

$$\begin{aligned} & \cdot 2\varphi_b + \psi + 2\varphi_b + \varphi_c = 0 \quad \uparrow \quad \text{--- (12) } 13 \\ & 2\varphi_c + \varphi_b + 2\varphi_c + \psi = 0 \quad \left\{ \begin{array}{l} 4\varphi_b + \varphi_c + \psi = 0 \\ \varphi_b + 4\varphi_c + \psi = 0 \end{array} \right. \quad \text{--- (13) } 14 \end{aligned}$$

$$\begin{aligned} & \cdot 2\varphi_b + \psi + \varphi_b + \psi + 2\varphi_c + \psi + \varphi_c + \psi = -p_h \\ & \boxed{3\varphi_b + 3\varphi_c + 4\psi = -p_h} \quad \text{--- (14)} \end{aligned}$$

$$(13) \cdot 1 \quad \varphi_c = -4\varphi_b - \psi \quad \text{--- (15)}$$

(16) ∈ (14) (15) ∈ ℝ ∩ ℤ

$$\varphi_b - 16\varphi_b - 4\psi + \psi = 0$$

$$15\varphi_b + 3\psi = 0$$

$$5\varphi_b + \psi = 0 \Rightarrow \underline{\underline{\psi = -5\varphi_b}} \rightarrow (17)$$

$$3\varphi_b + -12\varphi_b - 3\psi + 4\psi = -p_h$$

$$-9\varphi_b + \psi = -p_h \quad \text{--- (18)}$$

(18) 12 (17) ∈ ℝ ∩ ℤ

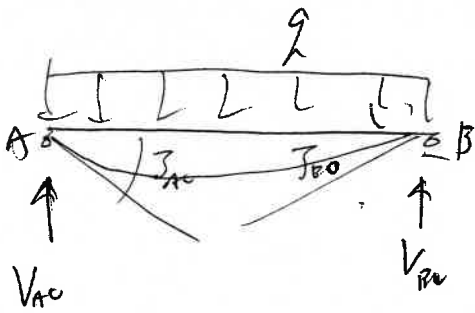
$$-9\varphi_b - 5\varphi_b = -p_h$$

$$-14\varphi_b = -p_h$$

$$\hookrightarrow \varphi_b = \frac{1}{14} p_h \quad \text{--- (19)}$$

(19) ∈ (17) ∈ ℝ ∩ ℤ

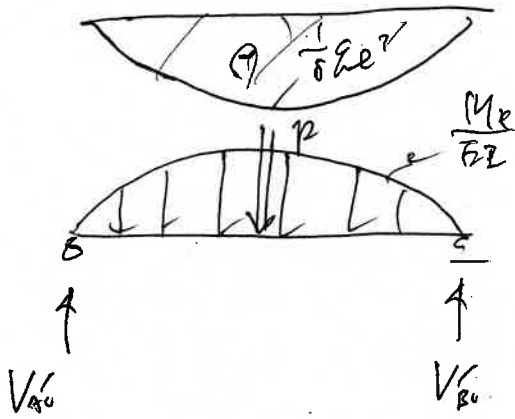
$$\psi = -5 \times \frac{1}{14} p_h = -\frac{5}{14} p_h \quad \text{--- (20)}$$



$$\sum M_A = -V_{B0}l + \frac{1}{2}ql^2 = 0$$

$$\therefore V_{B0} = \frac{1}{2}ql = V_{A0}$$

$$M_x = \frac{1}{2}qlx - \frac{1}{2}qx^2$$



~~$$P = \int_0^l \frac{M_x}{EI} dx$$~~

$$P = \int_0^l \frac{M_x}{EI} dx$$

$$= \frac{1}{EI} \left[\frac{1}{4}qlx^2 - \frac{1}{6}qx^3 \right]_0^l$$

$$= \frac{ql^3}{12EI}$$

~~$$\sum M_A = V_{B0}l - \frac{ql^3}{12EI} \times \frac{l}{2} = 0$$~~

$$\sum M_A = V_{B0}l - \frac{ql^3}{12EI} \times \frac{l}{2} = 0$$

$$V_{B0}' = \frac{ql^3}{24EI} = V_{A0}' = J_{A0} = -J_{B0}$$

$$C_{AB} = -\frac{2EI}{l} (2J_{A0} + J_{B0}) = -\frac{2EI}{l} \left(\frac{2ql^3}{24EI} - \frac{ql^3}{24EI} \right)$$

~~$$= -\frac{2EI}{l} \left(\frac{ql^3}{12EI} \right)$$~~

$$= -\frac{2}{l} \times \left(\frac{2-1}{24} \right) ql^3 = -\frac{ql^2}{12}$$

$$C_{BA} = -\frac{2EI}{l} (J_{A0} + 2J_{B0}) = -\frac{2EI}{l} \left(\frac{ql^3}{24EI} - \frac{2ql^3}{24EI} \right)$$

$$= \frac{1}{12} ql^2$$

$$M_A = M_{AB} = \frac{2EI}{l} (\theta_A + 2\theta_B - 3R) + C_{AB}$$

梁两端的 $\theta_A = \theta_B = R = 0$, $C_{AB} = -\frac{1}{12} ql^2$

$$M_A = -\frac{1}{12} ql^2$$

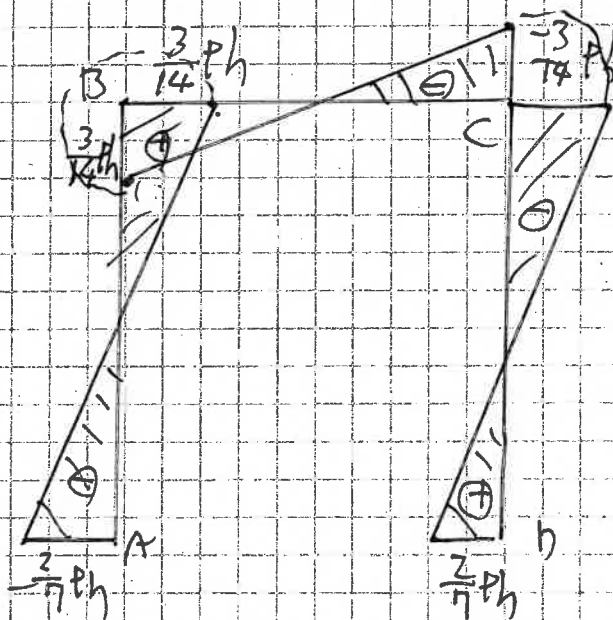
$$\left\{ \begin{aligned} \varphi_b &= \frac{1}{14} Ph, & \varphi_c &= -4 \times \frac{1}{14} Ph + \frac{5}{14} Ph = \frac{1}{14} Ph \\ \psi &= -\frac{5}{14} Ph \end{aligned} \right.$$

$$M_A = M_{db} = \frac{1}{14} Ph - \frac{5}{14} Ph = -\frac{4}{14} Ph = -\frac{2}{7} Ph$$

$$M_B = M_{bc} = 2 \times \frac{1}{14} Ph + \frac{1}{14} Ph = \frac{3}{14} Ph$$

$$M_C = M_{cd} = 2 \times \frac{1}{14} Ph - \frac{5}{14} Ph = -\frac{3}{14} Ph$$

$$M_D = -M_{dc} = -\frac{1}{14} Ph + \frac{5}{14} Ph = \frac{4}{14} Ph = \frac{2}{7} Ph$$



← 曲率正负号 →